

## 1. SC65F Incremental Optical Encoder (Solid Shaft)

### 1.1 Introduction:

SC65F is a solid shaft housing design, various of electrical interfaces and resolutions available, mounting by flange, highest protection grade IP65, compact product structure, high safety, suitable for high intensity mechanical movement fields.

### 1.2 Feature:

- Encoder external diameter  $\varnothing 61\text{mm}$ ; thickness 58mm; diameter of shaft  $\varnothing 15\text{mm}$ (keyway 5mm);
- Dimension of mounting flange 68mm\*68mm; installation hole distance 56mm\*56mm;
- Adopt non-contact photoelectric principle;
- Resolution up to 48000PPR;
- Reverse polarity protection;
- Short circuit protection

### 1.3 Application:

CNC machine tools, textile industry, packaging machinery and other industrial automation fields.

### 1.4 Connection:

- Radial cable (Standard length 1M)
- Radial socket (M18/M28 male socket)

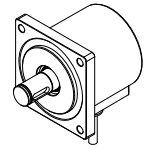
### 1.5 Protection:

IP65(Max)

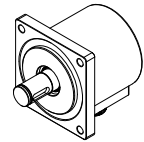
### 1.6 Weight:

About 590g

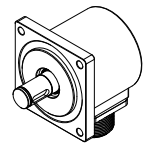
SC65F-T



SC65F-C  
SC65F-D

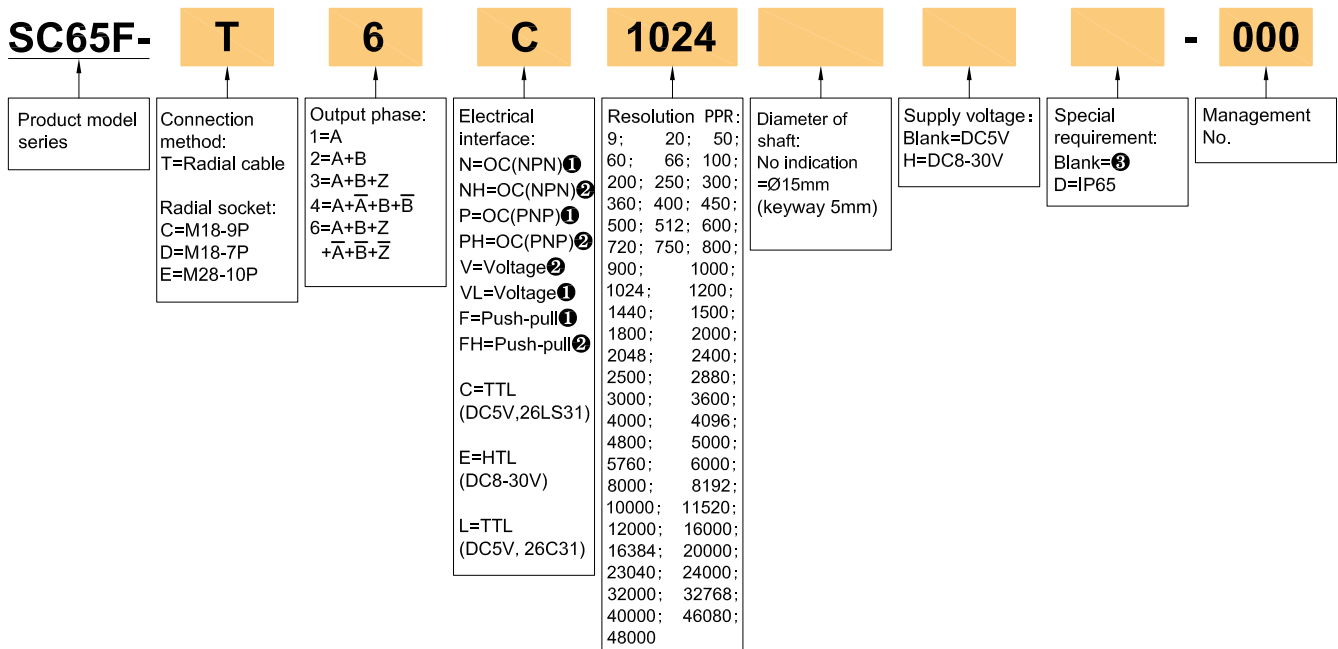


SC65F-E



## 2. Model Selection Guide

### 2.1 Model composition(select parameters)



### 2.2 Note

- Z signal is low level active.
- Z signal is high level active.
- None indicated for IP50 and cable length of 1M, if need to change the length C+number, the longest is 100M (expressed by C100). For the specific length of use, pls refer to page 2 of the provision of output circuit.

3. Output Mode

Electrical interface	Output circuit	Output wave form
<p>OC NPN open collector circuit</p>		<p>Phase A is ahead of B by <math>\frac{T}{4}</math>, viewing from shaft end, direction is clockwise rotation. (See dimensional drawings)</p> <p>CW direction →</p> <p>Z signal is low level active</p>
<p>OC PNP open collector circuit</p>		<p>Z signal is high level active</p>
<p>Push-pull</p>		<p>Z signal is high level active</p>
<p>Voltage</p>		<p>Z signal is high level active</p>
<p>TTL (DC5V)</p> <p>HTL (DC8-30V)</p>		<p>Phase A is ahead of B by <math>\frac{T}{4}</math>, viewing from shaft end, direction is clockwise rotation. (See dimensional drawings)</p> <p>CW direction →</p> <p>Z signal is high level active</p>

## 4. Electrical Parameters

Parameter Item	Output type	OC	Voltage	Push-pull	TTL	HTL	
Supply voltage		DC+5V±5% & DC8V-30V±5%			DC+5V±5%	DC8-30V±5%	
Consumption current		100mA Max			120mA Max		
Allowable ripple		≤3%rms					
Top response frequency		100KHz			300KHz	500KHz	
Output capacity	Output current	Input	≤30mA	Load resistance 2.2K	≤30mA	≤±20mA	≤±50mA
		Output	—		≤10mA		
	Output voltage	"H"	—	—	≥[ (Supply voltage) -2.5V]	≥2.5V	≥V <sub>CC</sub> -3 V <sub>DC</sub>
		"L"	≤0.4V	≤0.7V(less than 20mA)	≤0.4V(30mA)	≤0.5V	≤ 1V V <sub>DC</sub>
Load voltage		≤DC30V	—		—		
Rise & Fall time		Less than 2us(cable length: 2m)			Less than 1us (Cable length: 2m)		
Insulation strength		AC500V 60s					
Insulation resistance		10MΩ					
Mark to space ratio		45% to 55%					
Reverse polarity protection		✓					
Short-circuit protection		—			✓①		
Phase shift between A & B		90°±10° ( frequency in low speed)					
		90°±20° ( frequency in high speed)					
GND		Not connect to encoder					

① Short-circuit to another channel or GND(PNP is effective for Up) , permitted for max.30s.

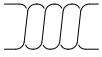



## 5. Mechanical Specifications

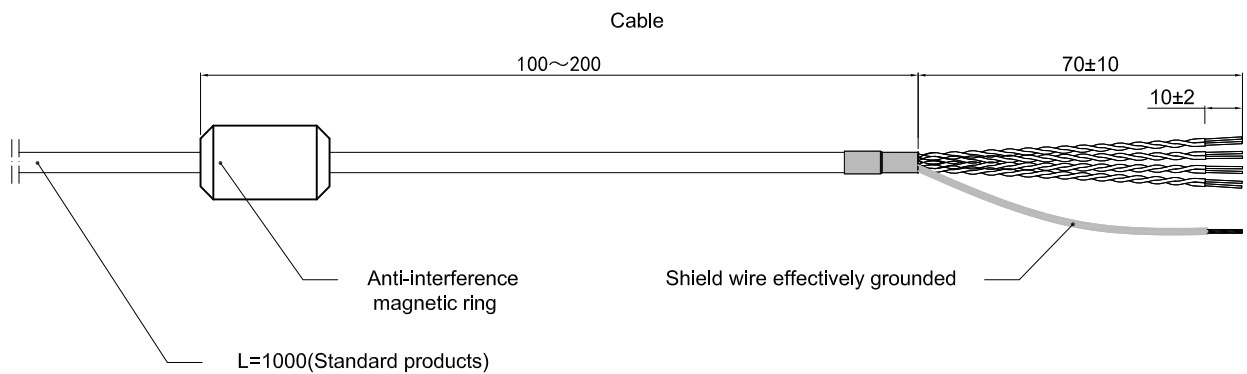
Diameter of shaft	Ø15mm (keyway 5mm)
Starting torque	Less than $10 \times 10^{-3} \text{N}\cdot\text{m}$
Inertia moment	Less than $3 \times 10^{-6} \text{kg}\cdot\text{m}^2$
Shaft load	Radial 30N; Axial 20N
Slew speed	$\leq 5000 \text{ rpm (IP50)}$ ; $\leq 3000 \text{ rpm (IP65)}$
Bearing Life	$1.5 \times 10^9$ revs at rated load(100000hrs at 2500RPM)
Shell	Aluminium alloy
Weight	About 590g

## 6. Environmental Parameters

Environmental temperature	Operating: $-20 \sim +90^\circ\text{C}$ (repeatable winding cable: $-10^\circ\text{C}$ ); Storage: $-25 \sim +95^\circ\text{C}$
Environmental humidity	Operating and storage: 35~85%RH(noncondensing)
Vibration(Endurance)	Amplitude 0.75mm,5~55Hz,2h for X,Y,Z direction individually
Shock(Endurance)	$490\text{m/s}^2$ 11ms three times for X,Y,Z direction individually
Protection	IP50 & IP65

7. Wiring Table

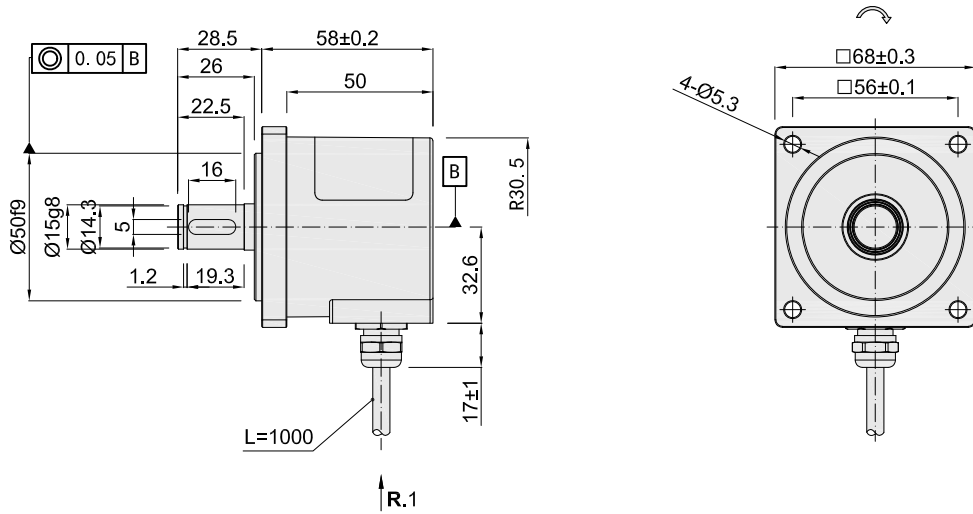
Socket pin definition (M18 9-pin male socket)	Socket pin definition (M18 7-pin male socket)	Socket pin definition (M28 10-pin male socket)	Wire colors (cable connection)	Signal	Explanation	Differential twisted pair
1	1	J	Red	Up	Power positive	
2	2	I	Black	Un	Power negative	
3	3	A	White	A	Signal wire	
6	-	B	White/BK	$\bar{A}$	Signal wire	
4	4	C	Green	B	Signal wire	
7	-	D	Green/BK	$\bar{B}$	Signal wire	
5	5	E	Yellow	Z	Signal wire	
8	-	F	Yellow/BK	$\bar{Z}$	Signal wire	
9	6	G	-	-		
-	7	H	-	-		
GND	Not connected to the encoder body					



Unit: mm

8. Basic Dimensions

8.1 SC65F-T



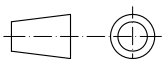
8.2 SC65F-C  
SC65F-D



8.3 SC65F-E



Unit: mm



- = Shaft rotation direction of incremental signal output
- R.1 = Radial cable (standard length 1M)
- R.2 = Radial socket (M18 7-pin & M18 9-pin male socket)
- R.3 = Radial socket (M28 10-pin male socket)

## 9. Caution

### 9.1 About vibration

Vibration act on encoder always cause wrong pulse, so we should pay attention to working place. More pulse per revolution, narrower groovy spacing of grating, more effect to encoder by vibration, when rev is low or stop, vibration act on shaft or main body would cause grating vibrating, so encoder might make wrong pulse.

### 9.2 Caution for wiring

- Use the encoder under the specified supply voltage. Please note that the supply voltage range may drop due to the wiring length.
- Do not put the encoder wiring and other power lines through the same duct, and do not use them by bundling in parallel.
- Please use twisted pair wires for the signal and power wires of encoder.
- Please do not apply excessive force to the cable of encoder, or it will may be damaged.

